MDMAE 2014
2014 International Conference on Mechanical Design, Manufacture and Automation Engineering
January 11–12, 2014, Phuket, Thailand

Abstract
2014 International Conference on Artificial Intelligence and Software Engineering (AISE2014)
2014 International Conference on Mechanical Design, Manufacture and Automation Engineering (MDMAE2014)
2014 International Conference on Global Economy, Commerce and Service Science (GECSS2014)
2014 International Conference on Education Reform and Modern Management (ERMM2014)

January 11-12, 2014, Phuket, Thailand

Conference Program Guide
TABLE OF CONTENTS

PART 1: PROGRAM SCHEDULE ................................................................. 2

PART 2: KEYNOTE SPEECHES ............................................................... 3
KEYNOTE SPEECH 1 ............................................................................. 3
KEYNOTE SPEECH 2 ............................................................................. 4

PART 3: ORAL SESSIONS ................................................................. 5
ORAL SESSION 1 ............................................................................... 5
ORAL SESSION 2 ............................................................................... 6
ORAL SESSION 3 ............................................................................... 8

PART 4: POSTER SESSION .............................................................. 10

PART 5: INSTRUCTIONS FOR PRESENTATIONS .............................. 13

PART 6: CONFERENCE VENUE ......................................................... 14

PART 7: CONTACT ............................................................................ 15
# PART 1: PROGRAM SCHEDULE

## January 11, 2014 (Saturday)

<table>
<thead>
<tr>
<th>Time</th>
<th>Event</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>09:00-12:00</td>
<td>Conference Registration</td>
<td>Lobby</td>
</tr>
<tr>
<td>14:00-18:00</td>
<td>Conference Registration</td>
<td>Cape Panwa Hotel</td>
</tr>
</tbody>
</table>

## Morning, January 12, 2014 (Sunday)

<table>
<thead>
<tr>
<th>Time</th>
<th>Event</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>09:00-09:15</td>
<td>Open Ceremony</td>
<td></td>
</tr>
<tr>
<td>09:15-10:00</td>
<td>Keynote Speech 1</td>
<td>Tamarind Bay room, Cape Panwa Hotel</td>
</tr>
<tr>
<td></td>
<td><strong>Prof. Akira Namatame</strong></td>
<td></td>
</tr>
<tr>
<td>10:00-10:15</td>
<td>Coffee Break</td>
<td>Tamarind Bay room, Cape Panwa Hotel</td>
</tr>
<tr>
<td>10:15-11:00</td>
<td>Keynote Speech 2</td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>Prof. Chih-Min Lin</strong></td>
<td></td>
</tr>
<tr>
<td>11:00-12:30</td>
<td>Oral Session 1</td>
<td></td>
</tr>
<tr>
<td></td>
<td><strong>AISE2014</strong></td>
<td></td>
</tr>
<tr>
<td>12:00-14:00</td>
<td>Buffet Lunch</td>
<td>Café Andaman, Cape Panwa Hotel</td>
</tr>
</tbody>
</table>

## Afternoon, January 12, 2014 (Monday)

<table>
<thead>
<tr>
<th>Time</th>
<th>Event</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>14:00-18:00</td>
<td>Oral Session 2</td>
<td>Tamarind I, Cape Panwa Hotel</td>
</tr>
<tr>
<td></td>
<td><strong>AISE2014&amp;MDMAE2014</strong></td>
<td></td>
</tr>
<tr>
<td>15:00-15:15</td>
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<td></td>
</tr>
<tr>
<td>14:00-18:00</td>
<td>Oral Session 3</td>
<td>Tamarind II, Cape Panwa Hotel</td>
</tr>
<tr>
<td></td>
<td><strong>GECSS2014&amp;ERMM2014</strong></td>
<td></td>
</tr>
<tr>
<td>15:00-15:15</td>
<td>Coffee Break</td>
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</tr>
</tbody>
</table>
PART 2: KEYNOTE SPEECHES

Keynote Speech 1: Systemic Risks and Resilience of Global Financial Networks

Speaker: Prof. Akira Namatame, University of Haute-Alsace, France
Time: 09:15-10:00, January 12, 2014
Location: Tamarind Bay room, Cape Panwa Hotel

Biography: Dr. Akira Namatame (www.nda.ac.jp/~nama) is Professor of Computer Science Department at National Defense Academy of Japan. He is well-known as an international research leader in the field of multi-agent modeling and socio-economic complexity. In the past ten years he has given over 30 invited talks, and over 10 tutorial lectures. He has also been a leading figure in the community of researchers working on socio-economic complexity, for instance as program leader in many international conferences in the fields. His research interests include multi-agent systems, complex networks, financial networks, evolutionary computation, and game theory. He is the editor-in-chief of Springer’s Journal of Economic Interaction and Coordination. He has published more than 250 refereed scientific papers, together with eight books on multi-agent systems, collective systems and game theory.

Abstract: The recent financial crises have made it clear that increasingly complex strategies for managing risk in individual financial institutions have not been matched by corresponding attention to overall systemic risks. The qualification of systemic risks lies in the systemic nature and risks to one system may present an opportunity to another system. The impacts of systemic risks challenge for secure the financial systems as well as many socio-economic systems. However the consequences of systemic risks are harder to predict and estimate and understanding the nature of systemic risks presents challenges to all of us.

In this talk I survey a number of interesting theoretical and empirical studies on systemic risks and introduces some fundamental analytical and simulation models on systemic risks. These models consider the interplay between the characteristics of individual institutions and the overall dynamics of the financial networks. These models basically focus on designing of regulation policies aimed at reducing systemic risk.

The network is only as strong as its weakest link, and trade-offs are most often connected to a function that models system performance management. In this talk I also introduce the issue of enhancing resilience of global financial networks.
Keynote Speech 2: Development of Fuzzy Neural Network and Fuzzy Cerebellar Model
Articulation Controller for Control Problems

Speaker: Prof. Chih-Min Lin, Chair Professor and Dean of Electrical and Communication Engineering
College, Yuan Ze University, Taiwan
Time: 10:15-11:00, January 12, 2014
Location: Tamarind Bay room, Cape Panwa Hotel

Biography: Prof. Chih-Min Lin is currently a Chair Professor and Dean of Electrical and Communication Engineering College, Yuan Ze University, Taiwan. He also serves as an Associate Editor of IEEE Trans. on Cybernetics; Asian Journal of Control; International Journal of Fuzzy Systems; Intelligent Automation and Soft Computing; and International Journal of Machine Learning and Cybernetics. He has been the Chair of IEEE Computational Intelligence Society Taipei Chapter, the Chair of IEEE Systems, Man, and Cybernetics Society Taipei Chapter, a Board of Governor of IEEE Taipei Session. He has been awarded as the Distinguished Research Professor from National Science Council in Taiwan, the Distinguished Engineering Professor from China Engineering Society in Taiwan, and the Distinguished Electrical Engineering Professor from Chinese Electrical Engineering Society in Taiwan. He has been invited to give 9 keynote speeches in the international conferences. He is now a Board of Governor of IEEE Systems, Man, and Cybernetics Society. His research interests include fuzzy systems, neural network, cerebellar model neural network, and intelligent control systems. He is an IEEE Fellow and IET Fellow. Till now he has published 147 journal papers and 158 conference papers.

Abstract: The neural-network based control technique has represented an attractive design method for control of dynamic systems. The most useful property of neural network is the ability to approximate linear or nonlinear mapping through learning. Based on this property, the neural-network-based controllers have been developed to compensate the effects of nonlinearities and system uncertainties, so that the stability, convergence and robustness of the control system can be improved. Recently, the recurrent fuzzy neural networks have been extensively presented. With the delayed feedback paths introducing dynamics to the model, the RFNN can be regarded as dynamic systems; they can learn and memorize the information of the system dynamics implicitly without assuming much knowledge about the structure of the system under consideration. The RFNN is a dynamic mapping network and is more suitable for describing dynamic systems. Moreover, based on biological prototype of human brain and improved understanding of the functionality of the neurons and the pattern of their interconnections in the brain, a theoretical model used to explain the information-processing characteristics of the cerebellum was developed independently by Marr (1969) and Albus (1971). Cerebellar model articulation controller (CMAC) was first proposed by Albus in 1974. CMAC is a learning structure that imitates the organization and functionality of the cerebellum of the human brain. That model revealed the structure and functionality of the various cells and fibers in the cerebellum. The core of CMAC is an associative memory which has the ability to approach complex nonlinear functions. CMAC takes advantage of the input-redundancy by using distributed storage and can learn nonlinear functions extremely quickly due to the on-line adjustment of its system parameters. CMAC is classified as a non-fully connected perceptron-like associative memory network with overlapping receptive-fields. It has good generalization capability and fast learning property and is suitable for a lot of applications. This talk will introduce several NN-based and CMAC-based adaptive learning systems; these systems combine the advantages of NN and CMAC adaptive learning ability, fuzzy inference property and control technique. In these systems, the on-line parameter training methodologies, using the gradient descent method and the Lyapunov stability theorem, are proposed to increase the learning capability. Moreover, the applications of these systems in nonlinear control systems; a motor-toggle servomechanism, an anti-braking system, a wing rock motion control system, a two-axis linear piezoelectric ceramic motor, a magnetic ball levitation system and a biped robot control system, are demonstrated.
**PART 3: ORAL SESSIONS**

**Oral Session 1: AISE2014**

**Time:** 11:00-12:30, January 12, 2014  
**Location:** Tamarind Bay room, Cape Panwa Hotel

**Oral Presentation**

<table>
<thead>
<tr>
<th>Title</th>
<th>Authors</th>
<th>Paper ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>Study of the Effectiveness of Various Feature Extractors for Human Face Recognition for Low Resolution Images</td>
<td>Soodeh Nikan and Majid Ahmadi</td>
<td>AISE-A102</td>
</tr>
<tr>
<td>Symmetric Alpha Stable Distribution Model Application in Detecting Double JPEG Compression</td>
<td>Ru ZHANG, Xiao-gang YU, Jing ZHAO and Jian-qi LIU</td>
<td>AISE-A019</td>
</tr>
<tr>
<td>Incorporate the Influence of Passenger Flow in Train Regulation of Urban Rail</td>
<td>Yao CHEN, Chu-chu MAO, Hai-nan ZHU and Hai-qi DONG</td>
<td>AISE-A027</td>
</tr>
<tr>
<td>Research on Nonnegative Tucker3 Decomposition in Krylov Sub-Space Calculation for Feature Extraction</td>
<td>Hai-jun WANG, Jia-xin MA and Fei-qi XU</td>
<td>AISE-A035</td>
</tr>
<tr>
<td>Basic Principles and Summative Assessment of New Horizon College English Network Teaching Software</td>
<td>Mei-yan LIU</td>
<td>AISE-A042</td>
</tr>
<tr>
<td>Language Structure Study Using Slot Alignment</td>
<td>Gend Lal PRAJAPATI and Kavita CHOU DHARY</td>
<td>AISE-A046</td>
</tr>
<tr>
<td>Performing Bayesian Inference Using Apache Hadoop MapReduce</td>
<td>Nipat Jongswatana and Wichian Premchaiswadi</td>
<td>AISE-A058</td>
</tr>
<tr>
<td>Mobile Phone APP Software Browsing Behavior using Clustering Analysis</td>
<td>Chui-yu CHIU, Ju-min LIAO, I-ting KUO and Po-chou SHIH</td>
<td>AISE-A062</td>
</tr>
<tr>
<td>A Novel Image Watermarking Scheme Using Firefly Algorithm</td>
<td>Charu Agarwal, Anurag Mishra, Arpita Sharma and Girija Chetty</td>
<td>AISE-A077</td>
</tr>
<tr>
<td>The Implementing of an Ontology-based Medical Decision Support System on Breast Cancer</td>
<td>Shu-hsien LIAO, Shu-li LIAO and Shao-qi LU</td>
<td>AISE-A082</td>
</tr>
</tbody>
</table>
### Oral Session 2: AISE2014&MDMAE2014

**Time:** 14:00-18:00, January 12, 2014  
**Location:** Tamarind I, Cape Panwa Hotel

#### Oral Presentation

<table>
<thead>
<tr>
<th>Title</th>
<th>Authors</th>
<th>Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Modelling and Analyzing Parallel Applications in Highly Distributed Systems</td>
<td>Alberto Núñez, Manuel Núñez, Mercedes G. Merayo and Sergio Núñez</td>
<td>AISE-A083</td>
</tr>
<tr>
<td>Web-based Training for Computer Science: Limitations and Recommendations</td>
<td>Hamid Yasinian</td>
<td>AISE-A093</td>
</tr>
<tr>
<td>Study of Intelligent Impedance Control for Robot Arm</td>
<td>Yoshishige Sato</td>
<td>AISE-A139</td>
</tr>
<tr>
<td>Spatio-Temporal Saliency Map and Its Application in Bitsteam Extraction for Scalable Video Coding</td>
<td>Wei LIU, Xu CHEN and Yong-sheng LIANG</td>
<td>AISE-A143</td>
</tr>
<tr>
<td>Obstacle Avoidance Technology of Autonomous Vehicle Based on the Cost Function</td>
<td>Yun-xiao SHAN, Bi-jun LI, Yun XIE and Teng LI</td>
<td>AISE-A145</td>
</tr>
<tr>
<td>An Optimal Image Matching Model</td>
<td>Yu-jian LI, Shao-feng ZENG, Yong YANG, David M. W. POWERS and Xi-bin JIA</td>
<td>AISE-A146</td>
</tr>
<tr>
<td>Restoration of Low-Light-Level Image Based on RBF Neural Network</td>
<td>Ke ZHANG and Li-hong NIU</td>
<td>AISE-A152</td>
</tr>
<tr>
<td>Integrated Approach to Generate Assembly Process Plan based on Heuristic Rule</td>
<td>Hong-Seok PARK, Jin-Woo PARK and Upendra TULADHAR</td>
<td>AISE-A164</td>
</tr>
<tr>
<td>Dynamic Performance Simulation and Analysis of Switched Reluctance Motor Based On Matlab/Simulink</td>
<td>Su-ying ZHOU and Rong QI</td>
<td>AISE-7</td>
</tr>
<tr>
<td>Performance Research in E-Learning</td>
<td>Bing WU and Xin XU</td>
<td>AISE-12</td>
</tr>
<tr>
<td>Developing Anytime SVM Training Algorithms for Large-Scale Data Classification</td>
<td>Rui HAN, Moustafa GHANEM, Andreas WILLIAMS and Yi-ke GUO</td>
<td>AISE-A009</td>
</tr>
<tr>
<td>On Automated Online Essay Scoring in Chinese EFL Writing Evaluation</td>
<td>Xi-ming YUAN</td>
<td>AISE-A015</td>
</tr>
<tr>
<td>Multiple Criteria Decision Analysis Based on Variable Fuzzy Data Envelopment Analysis</td>
<td>Qing SHUANG, Yun-long MA, Kai SHUANG, and Xiao-dong LV</td>
<td>AISE-A031</td>
</tr>
<tr>
<td>Research on GNAR-GARCH Model and Its Application in Modeling and Forecasting</td>
<td>Jia-xin MA, Fei-yun XU, Ren HUANG and Hai-jun WANG</td>
<td>AISE-A050</td>
</tr>
<tr>
<td>Kansei Evaluation and Modeling of AR Products</td>
<td>Kun-chieh WANG and Ling-hsuan WANG</td>
<td>AISE-A060</td>
</tr>
<tr>
<td>Study on Modulus of Resilience and CBR of Roadbed for Xinganling Islanded Frozen Soil and Swamped Land</td>
<td>Shu-zhen XIN, Yue-hong SU and Xiao-yan HUANG</td>
<td>AISE-A073</td>
</tr>
<tr>
<td>Novel Hybrid of Time-Delay Neural Network and Wavelets to Predict Rich-Frequency Patterns: Application to Gait Biomechanics</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Marzieh M. ARDESTANI and Zhong-min JIN  AISE-A151

Generation of Translation Tables Adequate for Example-based Machine Translation by Analogy
Tatsuya KIMURA, Jin MATSUOKA, Yusuke NISHIKAWA and Yves LEPAGE  AISE-A163

Study of Simple Modeling Test for Extraction of Optimum Cutting Fluids in Reaming
Rikio HIKIJI  MDMAE-M034

Developing Manufacturing Knowledge Portal System of Production Technology for Automobile/Mobile Components
Young-moo HEO, Jong-deok KIM, Kwang-ho SHIN and Sung-min BAE  MDMAE-M048

New Modelling Tested Method for Controlling of Object with Oscillation Features
Vadim ZHMUD  MDMAE-M057

Research on the Assembly Process and the Dynamic Visual Optimization Design of Articulatory Vibrating Screen
Jing JIANG, Shu-ying LIU and Bang-chun WEN  MDMAE-M060

Processing of Materials by Novel Electric Discharge Assisted Mechanical Milling
A. Calka  MDMAE-M061

Viscous Heating Effects in Electrokinetically Driven Flow of Non-Newtonian Fluids Through a Slit Microchannel
Chien-Hsin CHEN and Yunn-Lin HWANG  MDMAE-M062

Adhesion-Induced Failure of the Slender MEMS Structures
Yun LIU and Yin ZHANG  MDMAE-M066

Manufacture of Screw Turbine and Placement of the Generator in the Screw Turbine Shaft Used for Small-scale of Micro Hydro Electrical Generating
Hendra and Anizar Indrani  MDMAE-M106

Magnetic Flux Saturation Effect in the Analysis of an Eddy Current Retarder
Seongyoun Park, Kyihwan Park, Changhee Yoo and Jungkyu Hwang  MDMAE-M112

Design and Structure of a Novel 3-DOF Micro-CMM
Ali RUGBANI and Kristiaan SCHREVE  MDMAE-M113

A Study on Forging Technology of Oxygen-Free Copper for Electrode Body Parts of Solar Light
Dong-hwan PARK, Yun-hak TAK and Geun-ho KANG  MDMAE-M117

Multi-Modal Interaction Device
Yul Hee Kim, Sang-Kyu Byeon, Yu-Joon Kim, Dong-Soo Choi and Sang-Youn Kim  MDMAE-M127

Observation of Pin-pad Contact in between Micro-Scale Gap
Gang-il Cha, Seong-min Song, Hanseo Cho, Seungho Jeon, Myungkyu Kim and Sangseok Yu  MDMAE-M132

Morphology and Stoichiometry of Ultra-Thin Cerium Oxide Film on Rh(111)
Lap-hong CHAN and Junji YUHARA  MDMAE-M136

An Automated Delivery System for Hospital Logistics
Carlos Antonio ACOSTA CALDERON, Elara Rajesh MOHAN and Buck Sin NG  MDMAE-M144

Contribution of Smart Textiles for the Objective Assessment of Sleep Movements in Neurodegenerative Patients
M.M. TAVARES, N.J.R. BELINO and M.A. VAZ PATTO  MDMAE-4

Analysis on Mechanical Model and Strength for Drum of Towing Winch
Xiao-rong XU, Xing-man YANG, Zhi ZHOU and Gang CHEN  MDMAE-M055
Manufature of Screw Turbine and Placement of the Generator in the Screw Turbine Shaft Used for Small-scale of Micro Hydro Electrical Generating

Hendra\textsuperscript{1,a,*} and Anizar Indriani\textsuperscript{2,b}

\textsuperscript{1} Mechanical Engineering Dept University of Bengkulu, Indonesia
\textsuperscript{2} Electrical Engineering Dept University of Bengkulu, Indonesia

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Phone: +62-823 9186 9866

Keywords: Micro-hydro, Screw Turbine, Water, Generator

Abstract. Screw turbine was developed as alternative micro-hydro power plants. Its working principle is to use the river or irrigation with low discharge. The water flows into the turbine will drive the blades of screw turbine to rotate. Rotation of screw turbine will be forwarded to generator for converted into electrical energy. In this paper we will focus on the manufacturing process for small-scale of screw turbine to generate electricity voltage. Manufacturing process of screw turbine component as micro-hydro power plant consists of two components such as mechanical and electrical components. Mechanical components consist of a screw turbine, home of turbine screw, shaft of turbine and bearings. The manufacturing process includes the cutting plate process, drawing process and joining. Electrical component is a generator with the rotor (magnets) and the stator (coil) and then assembly the mechanical and electrical components. After the assembled all component then followed performance testing of the screw turbine and generator. From the manufacturing process of screw turbine and generator are obtained the results of rotation and electric voltage.

Introduction

Demand of requirement of current electrical energy are increase with the high growth of the community and the equipment used electrical energy, such as electricity for housing, electricity for transportation (electric rail), household appliances and etc. Electrical energy can be generated by power plants like hydroelectric power plant [1, 2], steam power plants, diesel power plants, solar power plants, and wind power plants and nuclear. A resource of energy for diesel power plants is decreased such as petroleum and also for steam power plants having some disadvantages such as expensive and environmentally unfriendly. This encourages people to searching for sources of energy and technologies of power generating alternative as generating power electric such as hydro, solar, and wind powers. For cultivate this energy source is require some equipment such as solar cell, water turbines and windmills.

Technology and equipment of generating power electric has been developed on a small scale and large to produce the electric voltage by using the energy water sources. Large-scale generating power electric produce the hundreds of thousands of megawatts with using large area and concentrated field such as lake or dam. For small-scale electric power can be obtained by utilizing a small area, discharge and head low. For examples is screw turbine[3,4] where as can be used for small area, decentralized and also source of the water obtained from the flow of the river and irrigation.

For areas that have a river or stream irrigation by using of screw turbine engines are very useful as power plants. Micro-hydro power plants with a screw turbine can be made by a simple manufacturing process includes cutting process, drawing, joining and assembly.
Focused in this study is on the process of manufacturing a component of micro-hydro power plants by a small-scale screw turbine mechanism with output rotation is 330 rpm. Power plant machine is expected to be used by the community in meeting the needs of a stable electrical energy.

Methodology Manufacture and Testing of Micro Hydro Power Plant with Screw Turbine

Micro-hydro power plants by utilizing screw turbine consists of two parts or components, namely:

1. Mechanical components which consist of a blade screw turbine and shaft, the screw turbine, shaft and bearings.
2. Electrical components as generator of electric which consists of a rotor and stator.

Component of micro hydro power plant with screw turbine includes:

1. Mechanical component of micro-hydro power plant
   Mechanical components micro hydro power plant consists of blade of screw turbine, housing turbine and frame holder of screw turbine. Screw turbine is rotated by water flow from irrigation or Small River that flows from height of head water about 1 meter or more. The component of screw turbines are shown in Fig. 1 and Fig. 2 show the dimension of screw turbine. Blade of screw turbine made of aluminum with a thickness of 1.5 mm, shaft of screw turbine from PVC material. Material of shaft and frame of holder screw turbine are steel and iron for turbine house as shown in Fig. 3.

2. Electrical components of micro hydro power plant
   Electrical components that used is a generator that functioning to convert the mechanical energy of the mechanical components (screw turbine) into electrical energy. Component generator consists of rotor and stator as shown in Figs. 3g and 3h.

Manufacture of mechanical components of micro hydro power plant (Screw turbine)

Manufacture process of micro-hydro power plants is done by making a screw turbine as a mechanical component. Stages of manufacture process of screw turbine consist of:

1. Preparation of materials component for the manufacture such as plate (aluminum, shaft, PVC pipes and bearings).
   Manufacture of screw turbine component consists of several steps:
   a. Cutting thin plate to form a circle and cutting of the half of upper circle parts to be molded into the blade screw with the drawing process.
   b. The process of forming screw blade with drawing blade is made with a 10 blade of screw turbine where as outer diameter of blade of screw turbine is 70.8 mm and inner diameter is 20.8 mm.
   c. Joining blade of screw turbine to shaft turbine.
   d. Manufacture of screw turbine house with rolling and welding processes.
   e. Assembling the entire components screw turbine.
3. Rotation testing of mechanical components of screw turbine.
The resulting of rotation testing is done by flowing water to rotate screw turbines and measured by tachometer. Rotation was measured by making a variation in height of the base frame screw turbine such as 450 mm, 550 mm and 650 mm with a total volume of water are 1 gallon and 100 liters.

**Electrical component manufacturing micro hydro power plant (generator)**

The resulting of electrical component is composed of generator where as consisting of stator and rotor. Rotor is part of generator that contains the magnet while stator contains the coil windings. Number of magnets used in rotor and stator is 6 magnet and 6 coil windings. Manufacturing process of generators includes:

1. Preparation generator components such as magnet rotor and coil windings stator.
2. Manufacture and testing of coil windings.

Number of coil windings is made according to the conditions generated by rotation of screw turbine. Testing of coil windings and magnet performed with the electric motor before the magnet and coil windings mount on a screw turbine and then electric motor output of the coil windings is measured using a Multimeter. After performance testing of coil windings and magnet followed by mounting of magnet and coil windings on the frame holder of screw turbine. The installation of magnets and coil windings to screw turbine are shown in Fig. 5. Results show that rotation of coil windings at 1400 rpm produced the voltage of 750 volts. While for 270 rpm rotation obtained voltage is 70 volts.
Performance of screw turbine depends on the volume of water flow and height head of water. When the volume of water flow and height head is big then the rotation of screw turbine becomes high. This is due to the contact area become large on blade of screw turbine and pressure the blade to move rotate. Results of measurement rotation of screw turbine are shown in Table 1. Table 1 and Fig. 6 shows that the highest rotation appears at the 650 mm of height head with volume of water 19 liters are 166.5 rpm. For height head 450 mm obtained the rotation of generated is 134 rpm. Results for volume of water 100 liters with a height of 650 mm obtained by rotation of 330 rpm and 450 mm at the head of 165 rpm. The result shows that the height head affects the rotation as for screw turbine with small dimension is obtained 165 rpm, 268 and 330 rpm.

Table 1. Rotation and head of screw turbine with volume of water 19 and 100 liters

<table>
<thead>
<tr>
<th>Volume (l)</th>
<th>Head (mm)</th>
<th>Putaran (rpm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>19</td>
<td>450</td>
<td>134</td>
</tr>
<tr>
<td>19</td>
<td>550</td>
<td>165</td>
</tr>
<tr>
<td>100</td>
<td>450</td>
<td>165</td>
</tr>
<tr>
<td>100</td>
<td>550</td>
<td>268</td>
</tr>
</tbody>
</table>

![Rotation (rpm) Vs Head Screw Turbin (mm)](image)

Figure 6. Rotation and head of screw turbine with volume of water 19 and 100 liters

Conclusion

The conclusions are given as following:

1. Performance of screw turbine depends on the volume of water flow and height head of water. When the volume of water flow and height head is big then the rotation of screw turbine becomes high. This is due to the contact area become large on blade of screw turbine and pressure the blade to move rotate.
2. Results of measurement rotation of screw turbine show the maximum value of rotation appear at the 650 mm of height head of water on 19 and 100 liters volume of water flow.
3. In this paper, manufacture of screw turbine with small dimension can be producing the rotation about 330 rpm.

Acknowledgement

This research was financially supported by the Ministry of Education and Culture Republic Indonesia.

References
